PROGRAMME

		KEYNOTE
09:30		Embedded camera for SMT component alignment Jef Horijon, Kulicke & Soffa, and Eric Janssen, Prodrive
10:30		Break
11:00		Deep learning for machine vision, identification and quality control Herbert ten Have, Fizyr
11:30	00	Poultry inspection optimization Dick Goudriaan, DVC
12:00		Giving artificial intelligence to industrial vision systems of Caterpillar Paola Jaramillo, Mathworks
12:30		Lunch
13:45		Machine vision for accurate detection and inspection in robotic factory automation Thomas Woudsma, Prodrive
14:15		Detecting tomato diseases using hyper-spectral imaging and deep learning Martin Bosgra, NHL
14:45		Performant embedded machine vision on low cost, low power devices Mario Vigliar, Sedeco
15:15		Break
15:45	3	Towards fully-automated driving: challenges and potential solutions Gijs Dubbelman, TU Eindhoven
16:15	25	Identification and localization of plasma cut steel products at Voortman Roy de Kinkelder, Saxion
16:45		Drinks